$D+M=$
CPS-M1-MSE

en Original instructions.
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## WARNING

Read all the safety information, instructions, images and technical data provided with this product.
Failure to observe the following instructions can result in electric shock, fire and/or serious injury.
Keep all the safety information and instructions in a safe place for future reference.

## Introduction

Your D+H service and sales partner
Safety in the building is not only provided by the product. Safety is created above all by competence. All D+H service and sales partners are certified and regularly trained SHEV specialist companies. They work closely with D+H Mechatronic AG as the manufacturer to implement comprehensive system solutions for SHEV and natural building ventilation. With holistic support and continuous quality assurance in every phase of the project: from consulting, planning and project configuration o installation, commissioning, maintenance and service. This means that the highest national and international quality standards are reliably fulfilled.

Installation and commissioning
The comprehensive network of $\mathrm{D}+\mathrm{H}$ service and sales partners is available to you for proper installation and commissioning. Our partner system guarantees that $\mathrm{D}+\mathrm{H}$ products are installed exclusively by trained and experienced technicians in compliance with the technical directives and regulations. Personal transfer and instruction of the operators are included.

Maintenance and repairs
Building operators are responsible for the functional reliability of safety devices in their own buildings.
Regular and proper maintenance ensures that your system will always be operational. As SHEV specialist companies, the D+H service and sales partners are optimally qualified for the maintenance. Owners/ operators can demonstrate at any time that they have fulfilled their obligation by means of a service contract.

Quality with a warranty
You receive extended warranty benefits for all D+H SHEV systems that were installed by a $\mathrm{D}+\mathrm{H}$ service and sales partner and are regularly maintained. Ask your local D+H service and sales partner about this.

Always in your neighbourhood
We are represented around the globe with our network of subsidiaries and exclusive partners.
Looking for a local D+H partner?
Simply visit our website:
www.dh-partner.com

## Safety information

230 V AC operating voltage!
Risk of injury from electric shock!

- Only an authorised, electrically skilled person is allowed to connect the power
- Keep children away from the controller
- Only use in dry spaces
- Only intended for installation indoors
- Only use unaltered D+H original parts


## Intended use

- Modular MSE controller for complex control tasks
- Can be used in the AdComNet SHEV bus system
- Combine lines and groups however you want
- Convenience functions for daily ventilation
- Only intended for installation indoors


## MSE functional principle

The following functions run simultaneously in the event of smoke detection and subsequent triggering of the MSE. 1:

1. supply and discharge After successful feedback, the smoke extraction fans are switched on. 2.
2. the smoke is removed via temperature-resistant smoke extraction fans These fans can be installed either on the roof, in the wall of the respective utilisation units or centrally. In the case of interior rooms, the smoke is led out of the building via an appropriate duct system. In doing so, it must be ensured that the smoke does not re-enter adjacent utilisation units. To avoid this undesirable effect, appropriate fire dampers can be installed within the duct system. 3
3. postflow openings near the floor are opened so that supply air can flow in at the required flow velocity within the low-smoke layer accordingly. If a free afterflow is not possible, fresh air is supplied mechanically. The smoke layer must not be destroyed.

Practical tip: For the implementation of complex smoke extraction scenarios, a combination of mechanical and natural supply air tracking is possible.

## Performance features

## General

Variable module technology for complex control requirements
Flexible system structure through mounting rail system for all modules and extensions
Connection of supply and communication through integrated plug connectors
Retrofittable modules in case of building modifications
Parameterisable MRA and ventilation functions via D+H Software SCS
Inputs and outputs monitored for line breakage and short circuit Connection of max. 30 fire detectors or 10 MRA control points per monitored line input
AdComNet bus system for seamless networking of modules within the CPS-M and other D+H AdComNet components
Flexible use of parameterisable, digital inputs and outputs

## 24 V DC

2x max. 10 A drive current per actuator module
Stabilised output voltage due to switching power supply technology No signal loss in case of mains failure due to integrated emergency power supply (72 hours)

## 230 V AC

Emergency power supply (72 hours)
Up to 45, 230 V AC drives can be connected per drive group (1840VA)
400 V AC
Fans can be controlled either via frequency converter, soft starter or directly.
Power supply via main switch and with automatic mains switchover if required.

## Important regulations

It is necessary to observe VDE 0833 for danger alarm systems, VdS 2221, VDE 0100 for electrical systems, DIN 18232 for SHEV systems, the provisions of the local fire brigade and of the energy supply company for the mains connection.

## EN 12101-10 Energy supply

EN 12101-7 Smoke extraction ducts
EN 12101-8 Smoke dampers
EN 12101-3 Fire gas fans
EN 12101-1 Smoke curtains

## Pictogram explanation

| OK | Control panel O.K. |
| :---: | :--- |
| $\vdots$ | Fault |
| -a. | SHEV alarm |

## Example of application



Basic module socket MS-D1-RR-TS

Supply module socket MS-S1-RD-TS

Expansion module socket MS-S1-DD-TS
 Bus termination module BTM-1-1
Is plugged into the last module socket.


## Control module－CM－BT1－D4－P2

－Central control element of the control panel（segment coupler）
－One CM controller module is required for each CPS－M
－Each CM controller module can manage up to 29 addition－ al modules（PSM，AM，TMA）
－AdComNet interfaces for implementing decentralised sys－ tems in combination with other AdComNet control panels
－ 1000 SCS links and 100 connectors possible
－USB interface for configuring the system and the con－ nected drives（only ACB），and for firmware updates of the control panel
－Integrated LEDs to indicate operation（green），fault （yellow），alarm（red）and AdComNet operation
－Status displays for all modules of the respective CPS－M as well as emergency operation of the individual lines and groups using the 3．5＂TFT touch panel
－Three user－programmable digital inputs for connecting buttons，switches，external controls etc．
－Two user－programmable，isolated change－over contacts， for example，for fault and alarm notifications
－Integrated event memory for system analysis and traceability
－Connection using removable spring－type terminals
－Conductor cross－sections max． $1.5 \mathrm{~mm}^{2}$ flexible
－Dimensions WxHxD：26x130x125 mm
－Installation on a 35 mm top hat rail in combination with a basic module socket

## Supply module－PSM－1－24－040


－Power supply of the control panel system
－Max． 40 A load current for each supply module depending on the power supply unit
－If a load current of more than 40 A is required，another PSM（including supply module socket）can be used．
－The PSM always provides power to the actuator and trigger modules used to the right of it
－Automatic toggling between mains supply and battery supply in case of a mains outage
－Max．battery capacity 26 Ah（battery type 6）
－ 72 hours of emergency supply time
－Integrated protection against excessive discharge
－Temperature－controlled charging voltage with external temperature sensor
－Integrated LED to indicate a fault（yellow）
－Two connections for peripherals that are and are not supplied with emergency power
－Connection using removable spring－type terminals
－Conductor cross－sections max． $2.5 \mathrm{~mm}^{2}$ flexible or for supply and battery $6 \mathrm{~mm}^{2}$ flexible
－Dimensions WxHxD：26x130×125 mm
－Installation on a 35 mm top hat rail in combination with a basic module socket or for more than one power supply unit with a supply module socket

## Control module－CM－B－1－D4－P2


－Central control element of the control panel（segment coupler）
－One CM controller module is required for each CPS－M
－Each CM controller module can manage up to 29 addition－ al modules（PSM，AM，TMA）
－ 30 SCS links and 10 connectors possible
－USB interface for configuring the system and the con－ nected drives（only ACB），and for firmware updates of the control panel
－Integrated LEDs to indicate operation（green），fault （yellow），alarm（red）and AdComNet operation
－Status displays for all modules of the respective CPS－M as well as emergency operation of the individual lines and groups using the 3．5＂TFT touch panel
－Three user－programmable digital inputs for connecting buttons，switches，external controls etc．
－Two user－programmable，isolated change－over contacts， for example，for fault and alarm notifications
－Integrated event memory for system analysis and traceability
－Connection using removable spring－type terminals
－Conductor cross－sections max． $1.5 \mathrm{~mm}^{2}$ flexible
－Dimensions WxHxD：26x130×125 mm
－Installation on a 35 mm top hat rail in combination with a basic module socket

## Trigger module－TMA－1－D4－D12


－Module for connecting trigger peripheral devices
－Two independent lines for connecting a max．of 10 SHEV buttons and 30 fire detectors per line（only detectors approved by D＋H may be used）
－Cables are monitored by the EM－L01 terminal module
－The SCS software can be used to configure the lines also as user－programmable digital inputs and outputs
－Integrated LEDs to indicate a fault（yellow）and alarm （red）
－Connection using removable spring－type terminals
－Conductor cross－sections max． $1.5 \mathrm{~mm}^{2}$ flexible
－Dimensions WxHxD：26x130x125 mm
－Installation on a 35 mm top hat rail in combination with an expansion module socket

## Actuator module－AM－1－2－10－24－D6－D2


－Module for connecting 24 V DC actuators
－ 2 independent groups for connecting drives，each with a total maximum current of 10 A
－The cable is monitored for breaks and short circuits via the terminal module EM－47K
－Each group is electronically protected against overload
－ 4 user－programmable digital inputs（e．g．ventilation button）
－ 2 user－programmable digital outputs（e．g．NOT CLOSED signal）
－ 2 integrated ACB interfaces for reading out and configuring the connected ACB drives
－Can be used with 24 V DC pole－changing drives， ACB drives，spring－return motors and magnets
－Virtual groups in connection with ACB drives possible
－Adjustable ventilation time and opening width for everyday ventilation
－Integrated LEDs to indicate a fault（yellow）and alarm （red）
－Connection using removable spring－type terminals
－Conductor cross－sections max． $2.5 \mathrm{~mm}^{2}$ Flexible
－Dimensions WxHxD：26x130x125 mm
－Installation on a 35 mm top hat rail in combination with an expansion module socket

## Actuator module－AM－B－1－2－10－24－D4－D2


－Module for connecting 24 V DC actuators
－ 2 independent groups for connecting drives，each with a total maximum current of 10 A
－The cable is monitored for breaks and short circuits via the terminal module EM－47K
－Each group is electronically protected against overload
－ 4 user－programmable digital inputs（e．g．ventilation button）
－ 2 user－programmable digital outputs（e．g．NOT CLOSED signal）
－Can be used with 24 V DC pole－changing drives
－Integrated LEDs to indicate a fault（yellow）and alarm （red）
－Connection using removable spring－type terminals
－Conductor cross－sections max． $2.5 \mathrm{~mm}^{2}$ Flexible
－Dimensions WxHxD：26x130x125 mm
－Installation on a 35 mm top hat rail in combination with an expansion module socket

Actuator module - AM-1-1-08-230-D4-D2


- Module for connecting 230 V AC actuators
- 1 group for connecting drives with a total maximum current of 8 A
- Up to 45 drives per AM 230 connectable
- D+H 230 V AC drives with SHEV fast mode (HS) are supported
- The cable is monitored for breaks and short circuits via the terminal module EM 230
- 2 user-programmable digital inputs (e.g. ventilation button)
- 1 user-programmable digital output (e.g. NOT CLOSED signal)
- Can be used with 230 V AC standard drives
- Adjustable ventilation time and opening width for everyday ventilation
- Integrated LEDs to indicate a fault (yellow) and alarm (red)
- Connection using removable spring-type terminals
- Conductor cross-sections max. $2.5 \mathrm{~mm}^{2}$ flexible (230 V AC) or $1.5 \mathrm{~mm}^{2}$ flexible ( 24 V DC)
- Dimensions WxHxD: 26x130x125 mm
- Installation on a 35 mm top hat rail in combination with an expansion module socket


## Digital I/O module - IOM-D1-1212



- 12 user-programmable digital inputs
- 12 user-programmable digital outputs
- The digital inputs can also be parameterised as LT inputs
- Integrated LEDs to indicate a fault (yellow) and alarm (red)
- Connection using removable spring-type terminals
- Conductor cross-sections max. $1.5 \mathrm{~mm}^{2}$ flexible
- Dimensions WxHxD: 26x130×125 mm
- Installation on a 35 mm top hat rail in combination with an expansion module socket

Bistable relay module - BRM-1-COC-0006

- Six user-programmable, isolated change-over contacts for switching signals with 24 V DC or 230 V AC
- change-over contacts as bistable version



## AD I/O module - ADM-AD1-1212-4



4 user-programmable multifunctional inputs (digital or analog)

- 8 user-programmable digital inputs
- 12 user-programmable digital outputs
- 4 virtual adjustable threshold switches per analog input from which a virtual user-configurable digital input is set or reset
- The digital inputs can also be parameterised as LT inputs
- Integrated LEDs to indicate a fault (yellow) and alarm (red)
- Connection using removable spring-type terminals
- Conductor cross-sections max. $1.5 \mathrm{~mm}^{2}$ flexible
- Dimensions WxHxD: 26x130x125 mm
- Installation on a 35 mm top hat rail in combination with an expansion module socket

Power packs PS-S1-24-20 and PS-S1-24-40


## Functions:

- Output: 24 V DC, 20 A or 40 A
- Installation on 35 mm top hat rail
- Low ripple
- Reverse-voltage protected and short-circuit resistant
- Multiple power supply units can be combined
- For each power supply unit, one PSM supply module is needed


## Technical data:

| Type | PS-S1-24-20 | PS-S1-24-40 |  |
| :--- | :--- | :--- | :---: |
| Rated input voltage | $230 \mathrm{~V} \mathrm{AC} \pm 15 \%$ |  |  |
| Frequency | 45 to 65 Hz |  |  |
| Nominal power | $530 \mathrm{VA} / 480 \mathrm{~W}$ | $1040 \mathrm{VA} / 960 \mathrm{~W}$ |  |
| Output voltage | $24 \mathrm{~V} \mathrm{DC} \pm 1 \%$ |  |  |
| Ripple | $<50 \mathrm{mVSS}$ |  |  |
| Output current | 20 A | 40 A |  |
| Short-circuit resistant | YES |  |  |
| Can be connected in parallel | YES |  |  |
| Reverse-voltage protected | YES |  |  |
| Input line connection | max. $6 \mathrm{~mm}^{2}$ star / max. $4 \mathrm{~mm}^{2}$ flexible |  |  |
| Output line connection | max. $6 \mathrm{~mm}^{2}$ star / max. $4 \mathrm{~mm}^{2}$ flexible |  |  |
|  | max. $16 \mathrm{~mm}^{2}$ star / max. $16 \mathrm{~mm}^{2}$ flexible <br> Dimensions WxHxD | $90 \times 130 \times 150 \mathrm{~mm}$ |  |
|  | $140 \times 130 \times 150 \mathrm{~mm}$ |  |  |

Technical data

| Type | CPS-M1-MSE-020-xxxx | CPS-M1-MSE-040-xxxx | CPS-M1-MSE-060-xxxx | CPS-M1-MSE-080-xxxx |
| :---: | :---: | :---: | :---: | :---: |
| Supply | $230 \mathrm{~V} \mathrm{AC}, \pm 15 \%, 45$ to 60 Hz |  |  |  |
| Performance* Performance in standby* | 530 VA / 480 W ca. 7.5 W | 1040 VA / 960 W ca. 8.5 W | 1570 VA / 1440 W ca. 16 W | 2080 VA / 1920 W <br> ca. 17 W |
| Output voltage Ripple | $\begin{gathered} 24 \mathrm{~V} \mathrm{DC} \pm 1 \% \\ <50 \mathrm{mV}_{\mathrm{ss}} \end{gathered}$ |  |  |  |
| Nominal output current | 20 A | 40 A | 60 A | 80 A |
| Mode of operation <br> - Monitoring <br> - Alarm state / ventilation | Continuous duty <br> Short-time duty ( $30 \%$ duty cycle) |  |  |  |
| Housing | Sheet steel |  |  |  |
| Colour | RAL 7035, light grey |  |  |  |
| Type of protection | IP 54 (VdS IP 30) |  |  |  |
| Protection class | I |  |  |  |
| Temperature range | -5 to $+40{ }^{\circ} \mathrm{C}$ |  |  |  |
| Air humidity | 5\% to 95\% RH |  |  |  |
| Installation acc. to ICE 61439 | up to $2000 \mathrm{~m} / \mathrm{u} \mathrm{MN}$ |  |  |  |
| Dimensions W x H x D | $500 \times 500 \times 210 \mathrm{~mm}$ | $600 \times 800 \times 250 \mathrm{~mm}$ | $600 \times 800 \times 250 \mathrm{~mm}$ | $800 \times 1000 \times 300 \mathrm{~mm}$ |
| * For 230 V AC systems plus the power of the NSV 401 and the connected 230 V AC drives |  |  |  |  |

## 24 V emergency supply

- Emergency supply time: 72 hours
- Only use VdS-approved batteries.
- The sum of the nominal currents of the drives and actuators that are triggered when there is an alarm must not exceed the max. permitted load of the respective battery type
- The required battery capacity has to be determined for each PSM.
- The sum of the required ampere-hours (Ah) of all components including a $30 \%$ reserve, must be smaller than the capacity of the battery

Standard batteries:
For each PS-S1-24-20 (+PSM): $2 \times$ battery type 5 (12 V, 18 Ah $\pm 15 \%$ )
For each PS-S1-24-40 (+PSM): 2 x battery type 6 (12 V, 26 Ah $\pm 15 \%$ )
A special battery calculator is available for the exact determination of the required battery capacity.

| Battery type | Max. permitted <br> load through <br> drives / actuators | Connector |
| :--- | :--- | :--- |
| Battery type 4 (12 Ah $\pm 15 \%)$ | 24 A | Flat plug <br> $6,35 \mathrm{~mm}$ |
| Battery type 5 (18 Ah $\pm 15 \%)$ | 36 A | hole cable <br> lug $\varnothing 5 \mathrm{~mm}$ |
| Battery type 6 (26 Ah $\pm 15 \%)$ | 52 A | C |

## ACB interface

ACB is used for secure communication between the drive and com patible $\mathrm{D}+\mathrm{H}$ control systems. It enables activation, diagnostics and configuration with perfect position, directly from the control panel. In this process, all status messages, such as the OPEN and CLOSED signals, opening stroke and drive errors are transmitted to the control panel. The ACB bus is based on an open Modbus RTU protocol via which the actuator can be directly controlled and queried.
Further information can be found in the D+H ACB Planning Manual.

## Max. Number of drives per ACB connection:

AM 24 = max. 20 ACB drives

AM 230 = max. 20 ACB drives (CDC-5-ACB = max. 15)
In conjunction with locking drives (VLD, FRA), a maximum of 10 drives (incl. locking drives) can be connected.

## Topology of the ACB bus line:

- Stub lines max. 15 m
- Total length incl. stubs max. 200m.
- To avoid interference, the cables from the drive to the AM module must be laid close together.

| Components | Approx. Ah required for 72 hours |
| :--- | :--- |
| Intrinsic consumption by CM | 0.52 Ah |
| CM supply of the modules | 0.018 Ah per module |
| PSM | 0.29 Ah |
| IOM | $0,26 \mathrm{Ah}$ |
| BRM | $0,21 \mathrm{Ah}$ |
| TMA | 0.58 Ah |
| AM | 0.43 Ah |
| AM 230 | $0,3 \mathrm{Ah}$ |
| Fire detector | 0.005 Ah |
| Smoke vent button | 0.014 Ah |
| 24 V DC Drives / actuators for <br> 180 sec. | 0.18 Ah (for each 1 A nominal <br> current) |
| Alarm devices 250 mA for 180 <br> sec. | 0.045 Ah |
| Devices and digital outputs with <br> an emergency supply (can be <br> adjusted using SCS) | 7.2 Ah (for each 100 mA output <br> current) |
| Digital outputs with an emer- <br> gency supply (can be adjusted <br> using SCS) | 3.6 Ah (for each 50 mA output <br> current) |
| Touch panel | 0.4 Ah |
| Required capacity = Sum of the required Ah plus a 30\% reserve |  |

## Declaration of conformity

We declare under our sole responsibility that the product described under "Technical Data" complies with the following directives

2014/30/EU, 2014/35/EU, 2011/65/EU
S.I. 2016/1091, S.I. 2016/1011, S.I. 2012/3032

Technical documents stored at
D+H Mechatronic AG, D-22949 Ammersbek

| Dirk Dingfelder | Maik Schmees |
| :--- | :--- |
| CEO | CTO |

06.07.2022

## Arrangement of the modules

- Each CM controller module can manage up to 29 additional modules (PSM, AM, TMA)
- The first PSM provides power to the CM module as well as to the AM and TMA modules to the right of it
- Each additional PSM always provides power only to the modules to the right of it
- This applies also to the emergency battery power. Therefore, the modules are to be distributed evenly across the PSM modules
- Due to the higher current consumption and shorter cable paths, the AM 24 modules are each to be used first next to the PSM module
- The total current of the drives respectively connected to the PSM must not exceed the output current of the respective power supply unit.



## Installation of the module sockets



## Removal of the module sockets



- The connections, particularly the earth connections, may be connected to the respective associated PSM supply module and components only. No cross-flow of current may occur
- System voltage 24 V DC and/or 230 V AC!
- If 24 V DC and 230 V AC cables are laid in the same cable duct in the control panel, it must be ensured that the insulation of each conductor must be designed for the highest nominal voltage ( $\leq \mathbf{2 5 0} \mathrm{V}$ ).
- A green-yellow core may only be used as protective earth conductor.


## Cables for D+H SHEV systems

When selecting and routing cables, regional installation requirements pertaining to electric cable systems and necessary safety devices, and/or directives pertaining to maintaining the function of electrical cables must be observed (e.g. MLAR guidelines for the fire protection requirements to be met by cable systems in Germany).

Note:
Due to the variety available on the market, no type designations are specified for these cables. Please contact your D+H Partner for this information.

Cable line (control panel - detector)
The cables are monitored for short circuits and line breaks.

## Wiring diagram (sample)


$6 \times 0,8 \varnothing(R T 45)$
10x 0,8 Ø (RT 45-LT)
SHEV operation panel
Approx. 1.5 m above upper edge of finished floor

6x 0,8 Ø (RT 45)
$10 \times 0,8 \varnothing(R T 45-L T)$

## Cable lengths and cross sections for Mot.a and Mot.b (AM 24 / 24 V drives)

Cable group (control panel - drive) At least three-wire design:

- 2 wires for supplying the drive (Mot.a/ Mot.b)
- For pole-changing drives, 1 additional wire for cable monitoring, through which the SHEV high-speed (HS) signal is also transmitted to the drive.
- For ACB drives, 2 additional wires for the bus connection.

| Total current | 1 A | 2 A | 3 A | 4 A | 5 A | 6 A | 7 A | 8 A | 9 A | 10 A |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $2 \times 1,5 \mathrm{~mm}^{2}$ | 120 | 60 | 40 | 30 | 24 | 20 | 17 | 15 | 13 | 12 | m |
| $2 \times 2,5 \mathrm{~mm}^{2}$ | 200 | 100 | 65 | 50 | 40 | 33 | 28 | 25 | 22 | 20 | m |

Cross-section $\left(\mathrm{mm}^{2}\right)=\frac{\text { cable length }(\mathrm{m}) \times \text { total current }}{80}$
80

## Cable lengths and cross sections for L A, L V, N and PE (AM 230 / 230 V drives)

- max. cable length 500 m
- min. cable cross section $1.5 \mathrm{~mm}^{2}$
- A maximum voltage drop of $6.5 \%$ ( $3 \%$ with third-party drives) on the cables is permitted
- Max. 45 drives can be connected to a group
- The following two formulas must always be used to calculate cable cross sections. The higher value must be used.

| Total power consumption | 200 VA | 500 VA | 800 VA | 1100 VA | 1400 VA | 1700 VA | 1840 VA |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $5 \times 1,5 \mathrm{~mm}^{2}$ | 167 | 167 | 167 | 132 | 104 | 85 | 79 | m |
| $5 \times 2,5 \mathrm{~mm}^{2}$ | 278 | 278 | 278 | 220 | 173 | 142 | 131 | m |
| $5 \times 4 \mathrm{~mm}^{2}$ | 444 | 444 | 444 | 351 | 276 | 227 | 210 | m |

Formula 1: Cross section $\left(\mathrm{mm}^{2}\right)=\frac{\text { Basic cable length }(\mathrm{m}) \times \text { total power of all Drives (VA) }}{96600}$
Formula 2: Cross section $\left(\mathrm{mm}^{2}\right)=\frac{\text { Basic cable length }(\mathrm{m})}{111}$


| No. | Name | Description |
| :--- | :--- | :--- |
| X2.1 | N+ | Output potential without an emergency supply for <br> ventilation functions, max. 500 mA |
| X2.2 | - | Reference potential (do not connect to P-) |
| X2.3 | + | Output potential with an emergency supply, max. <br> 500 mA |
| X2.4 | - | Reference potential (do not connect to P-) |
| X4 | TCSU1 | RJ12 connection of external battery temperature <br> sensor |
| X5.1 | BATT+ | Secondary power supply (battery), <br> max 40 A |
| X5.2 | BATT- | Primary power supply (power pack), <br> max 40 A |
| X6.1 | SNT+ |  |
| X6.2 | SNT- | mand |





| No. | Name | Description |
| :---: | :---: | :---: |
| X1.1 | n.c. | n.c. |
| X1.2 | NO 1 | Isolated change-over contact, max. $35 \mathrm{~V} / 1 \mathrm{~A}$, collective alarm (factory setting, can be programmed using SCS) |
| X1.3 | COM 1 |  |
| X1.3 | NC 1 |  |
| X2.1 | n.c. | n.c. |
| X2.2 | NO 2 | Isolated change-over contact, max. $35 \mathrm{~V} / 1 \mathrm{~A}$, general malfunction (factory setting, can be programmed using SCS) |
| X2.3 | COM 2 |  |
| X2.4 | NC 2 |  |
| X3 | TP-C1 | RJ12 connection for touch panel |
| X4.1 | Shield | AdComNet master interface |
| X4.2 | ACN D- |  |
| X4.3 | ACN D+ |  |
| X5.1 | Shield | AdComNet slave interface |
| X5.2 | ACN D- |  |
| X5.3 | ACN D+ |  |
| X6.5 | n.c. | n.c. |
| X6.4 | DI 1.2 | Freely configurable digital input, 0 to 28 V , active minus or plus, control panel OPEN (factory setting, can be programmed using SCS) |
| X6.3 | DI 1.3 | Freely configurable digital input, 0 to 28 V , active minus or plus, control panel CLOSED (factory setting, can be programmed using SCS) |
| X6.2 | DI 1.4 | Freely configurable digital input, 0 to 28 V , active minus or plus |
| X6.1 | - | Reference potential (do not connect to P-) |



Connection - Digital inputs and outputs


Battery for the clock of the event memory
The CM module has a built-in lithium battery on the underside, which buffers the internal clock of the event memory in the event of a power failure.
The battery should be replaced at least every 10 years.
Attention! Folgende Reihenfolge beachten:

1. Read out and save existing parameterization
2. Change battery. Battery type: Lithium cell CR1216
3. Read in parameterization again


## Further top hat rail levels for additional CPS-M modules

If a top-hat rail is not sufficient for the configuration of your system, a further top-hat rails can be integrated in the following way.
Further top-hat rail rows are assembled like the first row of the CPS-M (see «Arrangement of the modules » page 8 )
Connect the AdComNet master interface X4 on the CM module of the first row to the AdComNet slave interface X5 on the CM module of the additional row. If you need additional module rows, proceed in the same way.
You can connect to any CM via USB and use the connected rows as a common control panel.
LT inputs, lines and groups can be freely linked across all rows


## * Termination:

The AdComNet segment must be terminated with 2 resistors (110 $\Omega$ ).
The resistors must in each case be connected at the end of the cable.
Connections that are not used also have to be terminated!


Earth the segment shielding once.




| Nr. | Name | Beschreibung |
| :---: | :---: | :---: |
| X1.1 | NC 1 | Floating output 1 - normally closed * |
| X1.2 | COM 1 | Floating output 1-COM |
| X1.3 | NO 1 | Floating output 1 - normally open * |
| X1.4 | COM 1 | Floating output 1-COM |
| X2.1 | NC 2 | Floating output 2 - normally closed * |
| X2.2 | COM 2 | Floating output 2 - COM |
| X2.3 | NO 2 | Floating output 2 - normally open * |
| X2.4 | COM 2 | Floating output 2 - COM |
| X3.1 | NC 3 | Floating output 3 - normally closed * |
| X3.2 | COM 3 | Floating output 3-COM |
| X3.3 | NO 3 | Floating output 3-normally open * |
| X3.4 | COM 3 | Floating output 3-COM |
| X4.4 | COM 4 | Floating output 4 - COM |
| X4.3 | NO 4 | Floating output 4 - normally open * |
| X4.2 | COM 4 | Floating output 4-COM |
| X4.1 | NC 4 | Floating output 4 - normally closed * |
| X5.4 | COM 5 | Floating output 5-COM |
| X5.3 | NO 5 | Floating output 5-normally open * |
| X5.2 | COM 5 | Floating output 5-COM |
| X5.1 | NC 5 | Floating output 5 - normally closed * |
| X6.4 | COM 6 | Floating output 6-COM |
| X6.3 | NO 6 | Floating output 6 - normally open * |
| X6.2 | COM 6 | Floating output 6-COM |
| X6.1 | NC 6 | Floating output 6 - normally closed * |
| * $5 \ldots 30 \mathrm{~V}$ DC, $10 \mathrm{~mA} \ldots 3 \mathrm{~A} / 5 \ldots 265 \mathrm{~V} \mathrm{AC}, 10 \mathrm{~mA} . . .3 \mathrm{~A}, \cos \varphi=1$ |  |  |

The "Failsafe power failure" parameter can be used to define the state of the potential-free contact to be taken in the event of a failure of the mains and battery supply. If the "None" configuration is selected, the last status is retained.







| Nr. | Name | Beschreibung |
| :---: | :---: | :---: |
| X1.1 | DO 1.4 | freely configurable digital output 1.4 max. 50 mA , short-circuit-proof |
| X1.2 | DO 1.3 | freely configurable digital output 1.3 max. 50 mA , short-circuit-proof |
| X1.3 | - | Reference potential (do not connect to P-) |
| X1.4 | DO 1.2 | freely configurable digital output 1.2 max. 50 mA , short-circuit-proof |
| X1.5 | DO 1.1 | freely configurable digital output 1.1 max. 50 mA , short-circuit-proof |
| X2.1 | DO 2.4 | freely configurable digital output 2.4 max. 50 mA , short-circuit-proof |
| X2.2 | DO 2.3 | freely configurable digital output 2.3 max. 50 mA , short-circuit-proof |
| X2.3 | - | Reference potential (do not connect to P-) |
| X2.4 | DO 2.2 | freely configurable digital output 2.2 max. 50 mA , short-circuit-proof |
| X2.5 | DO 2.1 | freely configurable digital output 2.1 max. 50 mA , short-circuit-proof |
| X3.1 | DO 3.4 | freely configurable digital output 3.4 max. 50 mA , short-circuit-proof |
| X3.2 | DO 3.3 | freely configurable digital output 3.3 max. 50 mA , short-circuit-proof |
| X3.3 | - | Reference potential (do not connect to P-) |
| X3.4 | DO 3.2 | freely configurable digital output 3.2 max. 50 mA , short-circuit-proof |
| X3.5 | DO 3.1 | freely configurable digital output 3.1 max. 50 mA , short-circuit-proof |
| X4.5 | DI/AI 1.1 | freely configurable multifunctional input 1.1 * digital $0 . . .28 \mathrm{~V}$, active minus or plus analog $0 \ldots 10 \mathrm{~V}$ |
| X4.4 | DI/AI 1.2 | freely configurable multifunctional input 1.2 * digital $0 \ldots 28 \mathrm{~V}$, active minus or plus analog $0 \ldots 10 \mathrm{~V}$ |
| X4.3 | - | Reference potential (do not connect to P-) |
| X4.2 | DI/AI 1.3 | freely configurable multifunctional input 1.3 * digital $0 . . .28 \mathrm{~V}$, active minus or plus analog $0 \ldots 10 \mathrm{~V}$ |
| X4.1 | DI/AI 1.4 | freely configurable multifunctional input 1.4 * digital 0 ... 28 V , active minus or plus analog 0 ... 10 V |
| X5.5 | DI 2.1 | freely configurable digital input 2.1* digital $0 \ldots 28 \mathrm{~V}$, active minus or plus |
| X5.4 | DI 2.2 | freely configurable digital input 2.2 * digital $0 \ldots 28 \mathrm{~V}$, active minus or plus |
| X5.3 | - | Reference potential (do not connect to P-) |
| X5.2 | DI 2.3 | freely configurable digital input 2.3* digital $0 \ldots 28 \mathrm{~V}$, active minus or plus |
| X5.1 | DI 2.4 | freely configurable digital input 2.4 * digital $0 \ldots 28 \mathrm{~V}$, active minus or plus |
| X6.5 | DI 3.1 | freely configurable digital input 3.1 * digital $0 \ldots 28 \mathrm{~V}$, active minus or plus |
| X6.4 | DI 3.2 | freely configurable digital input 3.2* digital $0 \ldots 28 \mathrm{~V}$, active minus or plus |
| X6.3 | - | Reference potential (do not connect to P-) |
| X6.2 | DI 3.3 | freely configurable digital input 3.3* digital $0 \ldots 28 \mathrm{~V}$, active minus or plus |
| X6.1 | DI 3.4 | freely configurable digital input 3.4* digital $0 \ldots 28 \mathrm{~V}$, active minus or plus |
| * not galvanically isolated |  |  |




| No. | Name | Description |
| :---: | :---: | :---: |
| X1.1 | P- | Reference potential, max. 10 A (do not connect to -) |
| X1.2 | MOT.b 1 | Drive group 1, max. 10 A |
| X1.3 | MOT.a 1 |  |
| X1.4 | E/HS 1 | Monitoring wire / high-speed for actuator group 1 |
| X2.1 | P- | Reference potential, max. 10 A (do not connect to -) |
| X2.2 | MOT.b 2 | Drive group 2, max. 10 A |
| X2.3 | MOT.a 2 |  |
| X2.4 | E/HS 2 | Monitoring wire / high-speed for actuator group 2 |
| X3.1 | ACB.B 1 | ACB interface of drive group 1 |
| X3.2 | ACB.A 1 |  |
| X3.3 | ACB.B 2 | ACB interface of drive group 2 |
| X3.4 | ACB.A 2 |  |
| X4.4 | SGI 1 | Position transmitter for drive group 1 (not yet implemented) |
| X4.3 | - | Reference potential (do not connect to P-) |
| X4.2 | SGI 2 | Position transmitter for drive group 2 (not yet implemented) |
| X4.1 | - | Reference potential (do not connect to P-) |
| X5.4 | DO 2.1 | Freely configurable digital output 1.1, max. $50 \mathrm{~mA} /$ NOT CLOSED signal LT 2 |
| X5.3 | - | Reference potential (do not connect to P-) |
| X5.2 | DI 2.1 | Freely configurable digital input, <br> 0 to 28 V , active minus or plus / OPEN LT 2 |
| X5.1 | DI 2.2 | Freely configurable digital input, 0 to 28 V , active minus or plus / CLOSE LT 2 |
| X6.4 | DO 1.1 | Freely configurable digital output 2.1, max. $50 \mathrm{~mA} /$ NOT CLOSED signal LT 1 |
| X6.3 | - | Reference potential (do not connect to P-) |
| X6.2 | DI 1.1 | Freely configurable digital input, 0 to 28 V , active minus or plus / OPEN LT 1 |
| X6.1 | DI 1.2 | Freely configurable digital input, 0 to 28 V , active minus or plus / CLOSE LT 1 |

Connection - Vent buttons to AM 24 / AM-B 24



## Connection - AM 24 / AM-B 24 with pole-changing drives




Damper drive
2-point control


Further connection diagrams for holding solenoids, alarm devices / release fittings, 24 V DC supply etc. as download:



| No. | Name | Description |
| :--- | :--- | :--- |
| X1.1 | N | Neutral conductor input |
| X1.2 | L | Phase 230 V input |
| X2.1 | N | Neutral conductor output |
| X2.2 | L-OPEN | Phase 230 V OPEN direction output |
| X2.3 | L-CLOSE | Phase 230 V CLOSE direction output |
| X2.4 | E | Monitoring wire |
| X4.5 | - | Reference potential (do not connect to P-) |
| X4.4 | ACB + | Supply of the ACB interface |
| X4.3 | ACB.A | ACB interface of drive group |
| X4.2 | ACB.B |  |
| X4.1 | SGI | Position transmitter for drive group <br> (not yet implemented) |
| X5.4 | DO 1.1 | Freely configurable digital output 1.1, max. 50 mA / <br> NOT CLOSED signal LT |
| X5.3 | - | Reference potential (do not connect to P-) |
| X5.2 | DI 1.1 | Freely configurable digital input 1.1, <br> 0 to 28 V, active minus or plus / OPEN LT |
| X5.1 | DI 1.2 | Freely configurable digital input 1.2, <br> 0 to 28 V, active minus or plus / CLOSE LT |
| X6.4 | - | Reference potential (do not connect to P-) |
| X6.3 | FES | Fault NSV |
| X6.2 | - | Reference potential (do not connect to P-) |
| X6.1 | SES | Start NSV, max. 50 mA |

## Please Note:

If the AM 230 is used as a pure ventilation group, the line monitoring can be switched off. In this case, no EM 230 end module is required.

Connection - NSV 401 control and vent button to AM 230



## Connection - NSV 401 power supply and D+H drives




Connection - TMA


| No. | Name | Description (as RM/RT lines) |  |
| :---: | :---: | :---: | :---: |
| X1.1 | DO 2.3 | No function | - |
| X1.2 | DO 2.2 | No function |  |
| X1.3 | - | Reference potential (do not connect to P-) |  |
| X1.4 | DO 1.3 (S) | Fault output (RT line 1), max. 50 mA |  |
| X1.5 | DO 1.2 (A) | Alarm output (RT line 1), max. 50 mA |  |
| X2.1 | DO 1.1 (K) | Monitoring output (RT line 1), max. 50 mA |  |
| X2.2 | DI 1.1 (Z) | Reset input (RT line 1) |  |
| X2.3 | - | Reference potential (do not connect to P-) |  |
| X2.4 | LINIE 1 (T) | RT line 1, max. 50 mA |  |
| X2.5 | FE | Functional earth |  |
| X3.1 | DO 2.1 | No function |  |
| X3.2 | DI 2.1 | No function / Reset input fire alarm system |  |
| X3.3 | - | Reference potential (do not connect to P-) |  |
| X3.4 | LINIE 2 (R) | RM line 1, max. 50 mA |  |
| X3.5 | FE | Functional earth |  |
| X4.5 | FE | Functional earth | $\begin{aligned} & N \\ & \underset{\sim}{N} \\ & \underset{\sim}{D} \end{aligned}$ |
| X4.4 | LINIE 3 (R) | RM line 2, max. 50 mA |  |
| X4.3 | - | Reference potential (do not connect to P-) |  |
| X4.2 | DI 3.1 | No function |  |
| X4.1 | DO 3.1 | No function |  |
| X5.5 | FE | Functional earth | $\sim$$\pm$$\stackrel{ \pm}{=}$$\stackrel{\rightharpoonup}{\sim}$ |
| X5.4 | LINIE 4 (T) | RT Line 2 |  |
| X5.3 | - | Reference potential (do not connect to P-) |  |
| X5.2 | DI 4.1 (Z) | Reset input (RT line 2) |  |
| X5.1 | DO 4.1 (K) | Monitoring output (RT line 2), max. 50 mA |  |
| X6.5 | DO 3.2 (A) | Alarm output (RT line 2), max. 50 mA |  |
| X6.4 | DO 3.3 (S) | Fault output (RT line 2), max. 50 mA |  |
| X6.3 | - | Reference potential (do not connect to P-) |  |
| X6.2 | DO 4.2 | No function |  |
| X6.1 | DO 4.3 | No function |  |


| No. | Name | Description (as digital inputs/outputs) |
| :---: | :---: | :---: |
| X1.1 | DO 2.3 | Freely configurable digital output 2.3, max. 50 mA |
| X1.2 | DO 2.2 | Freely configurable digital output 2.2, max. 50 mA |
| X1.3 | - | Reference potential (do not connect to P-) |
| X1.4 | DO 1.3 (S) | Freely configurable digital output 1.3, max. 50 mA |
| X1.5 | DO 1.2 (A) | Freely configurable digital output 1.2, max. 50 mA |
| X2.1 | DO 1.1 (K) | Freely configurable digital output 1.1, max. 50 mA |
| X2.2 | DI 1.1 (Z) | Freely configurable digital input 1.1, 0 to 28 V , active minus or plus |
| X2.3 | - | Reference potential (do not connect to P-) |
| X2.4 | LINIE 1 (T) | No function |
| X2.5 | FE | Functional earth |
| X3.1 | DO 2.1 | Freely configurable digital output 2.1, max. 50 mA |
| X3.2 | DI 2.1 | Freely configurable digital input $2.1,0$ to 28 V , active minus or plus |
| X3.3 | - | Reference potential (do not connect to P-) |
| X3.4 | LINIE 2 (R) | No function |
| X3.5 | FE | Functional earth |
| X4.5 | FE | Functional earth |
| X4.4 | LINIE 3 (R) | No function |
| X4.3 | - | Reference potential (do not connect to P-) |
| X4.2 | DI 3.1 | Freely configurable digital input 3.1, 0 to 28 V , active minus or plus |
| X4.1 | DO 3.1 | Freely configurable digital output 3.1, max. 50 mA |
| X5.5 | FE | Functional earth |
| X5.4 | LINIE 4 (T) | No function |
| X5.3 | - | Reference potential (do not connect to P-) |
| X5.2 | DI 4.1 (Z) | Freely configurable digital input 4.1, 0 to 28 V , active minus or plus |
| X5.1 | DO 4.1 (K) | Freely configurable digital output 4.1, max. 50 mA |
| X6.5 | DO 3.2 (A) | Freely configurable digital output 3.2, max. 50 mA |
| X6.4 | DO 3.3 (S) | Freely configurable digital output 3.3, max. 50 mA |
| X6.3 | - | Reference potential (do not connect to P-) |
| X6.2 | DO 4.2 | Freely configurable digital output 4.2, max. 50 mA |
| X6.1 | DO 4.3 | Freely configurable digital output 4.3, max. 50 mA |




Connection - TMA to fire alarm system (FAS)


## Description of the inputs and outputs

| Designation | Description |
| :---: | :---: |
| - | Reference potential / negative: used as the reference potential for external peripherals (e.g. SHEV operation panel or LT). <br> May not be connected to P-. <br> The reference potentials of more than one power supply module may not be connected together. |
| ACB.A x / ACB.B x MOT.a x / MOT.b x | Group (ACB): used for the connection of bus-capable drives. <br> ACB.A $x$ and ACB.B $x$ are necessary for communication with the drives. <br> MOT. a x and MOT.b x are necessary for supplying the connected drives. <br> The maximum output current of the supply is 10 A . <br> The supply is permanently short-circuit resistant and the fuse used is self-resetting. |
| ACN D+ / ACN DShield | AdComNet connection: used for interconnecting more than one CPS-M1 and for interconnecting with ACN-CM501, ACN-IO501, ACN-BI501-USB and ACN-GW501-MRTU. <br> If this connection is not used, it must nevertheless be terminated with a resistor (110 Ohm). |
| BATT+ / BATT- | Battery connection: may only be used for connecting the secondary power supply (battery). |
| COM x / NC x / NO x (monostable, CRM | Isolated output: used for the triggering of external systems. <br> The maximum contact current is 1 A . <br> The minimum contact current to ensure permanent safe operation is 10 mA . <br> The maximum contact voltage is 35 V DC. <br> The contact is not suitable for switching 230 V AC. <br> The output can be supplied with emergency power. This is to be taken into consideration in the battery capacity calculation. |
| COM x / NC x / NO x (bistable, BRM) | Isolated output: used for the triggering of external systems. <br> The maximum contact current is 3 A . <br> The minimum contact load to ensure permanent safe operation is $5 \mathrm{~V} / 10 \mathrm{~mA}$. <br> The maximum contact voltage is 30 V DC or 265 V AC. |
| DI X.x | Digital input: used for the evaluation of switch signals. <br> The input voltage range is $0 \mathrm{~V} D C$ to 28 V DC. <br> The pull-up resistor for the evaluation of an active negative signal is integrated. <br> The pull-down resistor for the detection of an active positive signal is integrated. <br> The switching contact is briefly ( $<100 \mathrm{~ms}$ ) loaded with 16 mA . <br> The input DI 1.1 of the controller module cannot currently be used. |
| DO x.x | Digital output: used for the triggering of displays or relays. <br> The output voltage range of an activated output is 17 V DC to 25 V DC. <br> The output voltage range applies for a maximum output current of 50 mA . <br> The connection is permanently short-circuit resistant and the fuse used is self-resetting. <br> If the output is deactivated, the output is open / has a high resistance. <br> Active negative inputs cannot be switched using the output. <br> The output can be supplied with emergency power. This is to be taken into consideration in the battery capacity calculation. |
| FE | Functional earth: can be used as the cable shielding connection when connecting a smoke detector line. May only be used as a cable shielding connection. |
| LINE / RT x | Line connection: used for connecting a smoke detector line or an SHEV operation panel line. Furthermore, external systems (e.g. fire detectors) can be connected. |
| LINE / RM x | A maximum of 30 smoke detectors or 10 SHEV operation panels can be connected. The connection is permanently short-circuit resistant and the fuse used is self-resetting. Cable monitoring is performed via the EM-L01. |
| MOT.A x / MOT.B x E/HS | Group (polarity change): used for the connection of conventional pole-changing drives. MOT.A x and MOT.B x are necessary for the supply and for controlling the direction. <br> The maximum output current of the supply is 10 A . <br> The supply is permanently short-circuit resistant and the fuse used is self-resetting. $\mathrm{E} / \mathrm{HS}$ is used for cable monitoring and for triggering the high-speed function. |
| n.c. | The terminal is not connected. |
| N+ | Operating voltage not supplied with emergency power: used for the supply of external peripherals. The output voltage range is $22 \mathrm{~V} D C$ to 24 V DC. <br> The maximum output current is 440 mA . |
| P- | Group reference potential / group negative: used as the reference potential for external drives (e.g. spring return actuators). <br> May not be connected to - <br> The group reference potentials of more than one power supply module may not be connected together. |
| + | Operating voltage supplied with emergency power: used for the supply of external peripherals. <br> The current consumption of the connected peripherals must be taken into consideration in the battery capacity calculation. <br> The output voltage range is $19 \mathrm{~V} D C$ to 27 V DC . <br> The maximum output current is 440 mA . |
| SGI x | This function has not yet been implemented. |
| SNT+ / SNT- | Mains power connection: may only be used for connecting the primary power supply (power pack). |
| TCSU1 | Temperature sensor connection: may only be used for connecting the TCSU1-RJ12. The maximum cable length to ensure permanent safe operation is 2 m . |
| TP-C1 | Touch panel connection: may only be used for connecting the TP-C1-35-RJ12. |

The D+H Service and Configuration Suite (SCS) is used for commissioning and programming.


Functions programmable via SCS:

CM :


## Standard configurations Controller Module (CM)

The isolated outputs from Controller Module are pre-configured by all standard control panels. The terminal X1 is for general fault and the terminal X2 for general alarm signals. The digital inputs X6.2 and X6.3 are pre-configured for general open- and general close- signals.

AM 24 :


TMA :

| 1. Designation |
| :--- |
| Line 1 |
| 2. Settings |
| Designation: $\square$ |
| $\square$ RM can only be locally reset |
| $\square$ Line fault tnggers alam |
| $\square$ Two-detector dependency |
| $\square$ Reset in case of pending alam on the RM line |
| $\square$ RT-Closed input generating pulse |
| $\square$ Alam delay $\quad 0 \quad$ nax. 20 characters) |
| Linetype: Standard |
| Apply $\quad$ Cancel |

AM 230 :


## Alarm with HS

ATTENTION! This function must only be used in conjunction with corresponding $\mathrm{D}+\mathrm{H}$ high speed drives.
If $\mathrm{D}+\mathrm{H}$ drives without high speed or third-party drives are connected, activation can destroy the drive!

## Description of the software functions

| Designation | Connection | Description |
| :---: | :---: | :---: |
| Digital output | Output inverted | The output issues the status of the link inverted. |
|  | Functionality selection | SHEV link: Alarm / Alarm Reset / Alarm Pulse / Fault / Not Closed |
|  |  | Ventilation link: Not Closed / LT Open forwarding / LT Closed forwarding |
|  | Supplied with emergency power | The output is also triggered in the event of a mains outage. An additional 0.072 Ah is to be taken into consideration in the battery capacity calculation. Furthermore, the current consumption of the connected peripherals is to be taken into consideration. |
|  | Functionality | SHEV link: Alarm / Alarm Pulse / Alarm Reset and RT Closed / Alarm and Alarm Reset with RT Closed / Fault |
|  |  | Ventilation link: LT Open / LT Closed / LT Stop / LT Open pulse / LT Closed pulse / LT Open and Closed pulse / LT Closed and Open pulse / LT Open pulse and Closed pulse |
| Digital input | Inverted | The status of the input is forwarded to the link inverted. |
|  | Active negative | The input is activated if switched to -. |
|  | Active positive | The input is activated if switched to $\mathrm{P}+$ or $\mathrm{N}+$. |
| Group | Actuator type | The group is used for triggering ACB drives or pole-changing drives. The type used must be selected for each group. |
|  | Alarm re-clocking | The group will be triggered every 2 minutes for 30 minutes in the event of an alarm. This function is a requirement of VdS 2581. |
|  | Open - running time limit | The group moves in the OPEN direction for the set time if the ventilation button is switched to the OPEN direction. |
|  | Open - retriggering | The group once more moves in the OPEN direction for the set time if the ventilation button is again switched to the OPEN direction. |
|  | For alarm Closed | The group moves in the CLOSED direction if the SHEV link to which the group is assigned is triggered. |
|  | For communication fault Closed | The group moves in the CLOSED direction if a communication fault occurs within a link to which the group is assigned. |
|  | Group fault triggers alarm | In the event of a group fault (e.g. a monitoring cable is interrupted or an addressed ACB drive is not available), the SHEV link to which the group is assigned is triggered. |
|  | Ventilation time active | The group automatically moves in the CLOSED direction upon expiry of the set ventilation time. |
|  | Mains outage CLOSED | The group automatically moves in the CLOSED direction in the event of a mains outage. Only the control panel groups move in the CLOSED direction in the event of a mains outage. Groups in the same link belonging to another CPS-M are not affected by this. |
|  | Storage operation OPEN | The group moves in the OPEN direction when a ventilation button of the ventilation link is pressed once. |
|  | Storage operation CLOSED | The group moves in the CLOSED direction when a ventilation button of the ventilation link is pressed once. |
|  | Stop-hold function | The supply cables MOT.A $x$ and MOT.B $x$ are short-circuited in the Stop status. A short circuit between these two cables can no longer be recognized as being a fault in this status. |
|  | Button operation OPEN | The group moves in the OPEN direction for as long as the ventilation button of the ventilation link is pressed. |
|  | Button operation CLOSED | The group moves in the CLOSED direction for as long as a ventilation button of the ventilation link is pressed. |
| Line | Line fault triggers alarm | In the event of a line fault (e.g. an interrupted cable), the SHEV link to which the line is assigned is triggered. |
|  | Smoke detector can only be locally reset | A smoke detector alarm cannot be reset by pressing the "SHEV CLOSED" button on the SHEV button panel. It is possible to reset the alarm via the touch panel. |
|  | Two-detector dependency | (Only with SD-O 371/FO 1362) Alarm will be triggered only, if at least two smoke detectors of one line respond. False alarm of one smoke detector will be prevented. Two smoke detectors in one room must be always installed. If only one smoke detector is connected to one line, switch must be on OFF! |
| Isolated output | Output inverted | The output issues the status of the link inverted. |
|  | Functionality selection | SHEV link: Alarm / Alarm Reset / Alarm Pulse / Fault / Not Closed Ventilation link: Not Closed / LT Open forwarding / LT Closed forwarding |
|  | Supplied with emergency power (monostable, CM) | The output is also triggered in the event of a mains outage. This must be taken into consideration in the battery capacity calculation. |
|  | Failsafe in case of power failure (bistable, BRM) | With this the state of the potential-free contact can be defined, which is to be taken in case of a failure of the mains and battery supply. <br> If the "None" configuration is selected, the last status is retained. |
| Event log | internal | All status changes of the CPS-M are written with time stamp in an event log. These can be read out via the SCS software. |



Start screen

- Displays the overall status of the control panel


Settings

- Setting the display language


TMA - Trigger module

- Display of the module status
- Status display of the lines
- Switch on and off, and resetting the lines
- Status display of the inputs and outputs



## Modules

- Overview of all modules used
- Display of the respective statuse similar to the LEDs on the respective module


IOM - I/O module

- Display of the module status
- Display of the status of the inputs and outputs


CM - Control module

- Display of the module status
- Display of the status of the inputs and outputs



## BRM - Relay module

- Display of the module status
- Display of the status of the inputs and outputs

AM 230 - Actuator module

- Display of the module status
- Status display of the group
- Status display of the inputs and outputs

Ventilation button or SHEV button with RT 45-LT ventilation function required.


## Operation - Weather automation

With connected wind or rain detector.
When the corresponding sensor is triggered, the control panel group
is closed. In case of an SHEV alarm, the system also starts in wind or rain.
Do not ventilate using the smoke vent button, as otherwise there is a risk of wind or water damage.
If gap ventilation is desired in bad weather, the weather automation can be switched off using an optional automatic switch.
If no automatic switch is present, gap ventilation is not possible in poor weather. If the weather automation is switched on, the system closes in case of wind or rain.
It does not open again automatically after the wind or rain stops. Opening the system for ventilation using the ventilation button.


## Operation - SHEV



Safety system, protects human life and real property value! Function check once a year by a specialist
company authorised by the manufacturer.


## Manual opening with smoke vent button

1

(2)

3

4


Automatic opening with fire detector
1

3


Automatic opening through external control (e.g. central fire alarm)
(1)

External control

(2) К RT 45

2
$\Rightarrow$


3


## Operation - Closing after alarm



## Warranty

You receive a 2-year warranty on all D+H articles from the documented date of handover until max. 3 years after the delivery date, provided that the installation/commissioning was carried out by an authorised D+H service and sales partner.
When connecting D+H components to external system or mixing D+H products with parts from other manufacturers.

## Disposal

Electrical devices, accessories, batteries and packaging should be recycled in an environmentally responsible manner. Do not throw electrical devices and batteries into the household waste!
Only for EU countries:
In accordance with European Directive 2012/19/EU pertaining to waste electrical and electronic equipment and its implementation in national law, usable electrical devices must be collected separately and submitted for environmentally responsible recycling.


## Maintenance and cleaning

Carried out once a year by a specialist company authorised by the device manufacturer.
Carry out cleaning and maintenance work only when the system is de-energised.
Replace the inspection plate, maintain the operational book.
The inspection and maintenance must take place in accordance with the $\mathrm{D}+\mathrm{H}$ maintenance instructions.
The respective current D+H maintenance instructions are authoritative. An authorised $D+H$ specialist company receives this automatically and has been given special training by $\mathrm{D}+\mathrm{H}$ in carrying out this maintenance.

The following tests must be carried out during maintenance:

- External expert assessment / inspection of the system components
- Checking all relevant voltage supply units
- Function test of the connected system components
- Logging the proper completion of maintenance and
- Labelling in accordance with requirements

Only original D+H spare parts may be used. Repairs are carried out by $\mathrm{D}+\mathrm{H}$ exclusively.
Wipe off dirt with a dry, soft cloth.
Do not use any detergents or solvents.

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